

Cruise report, expedition 64PE-549
Texel – Texel, the Netherlands (22-09 – 08-10-2025)

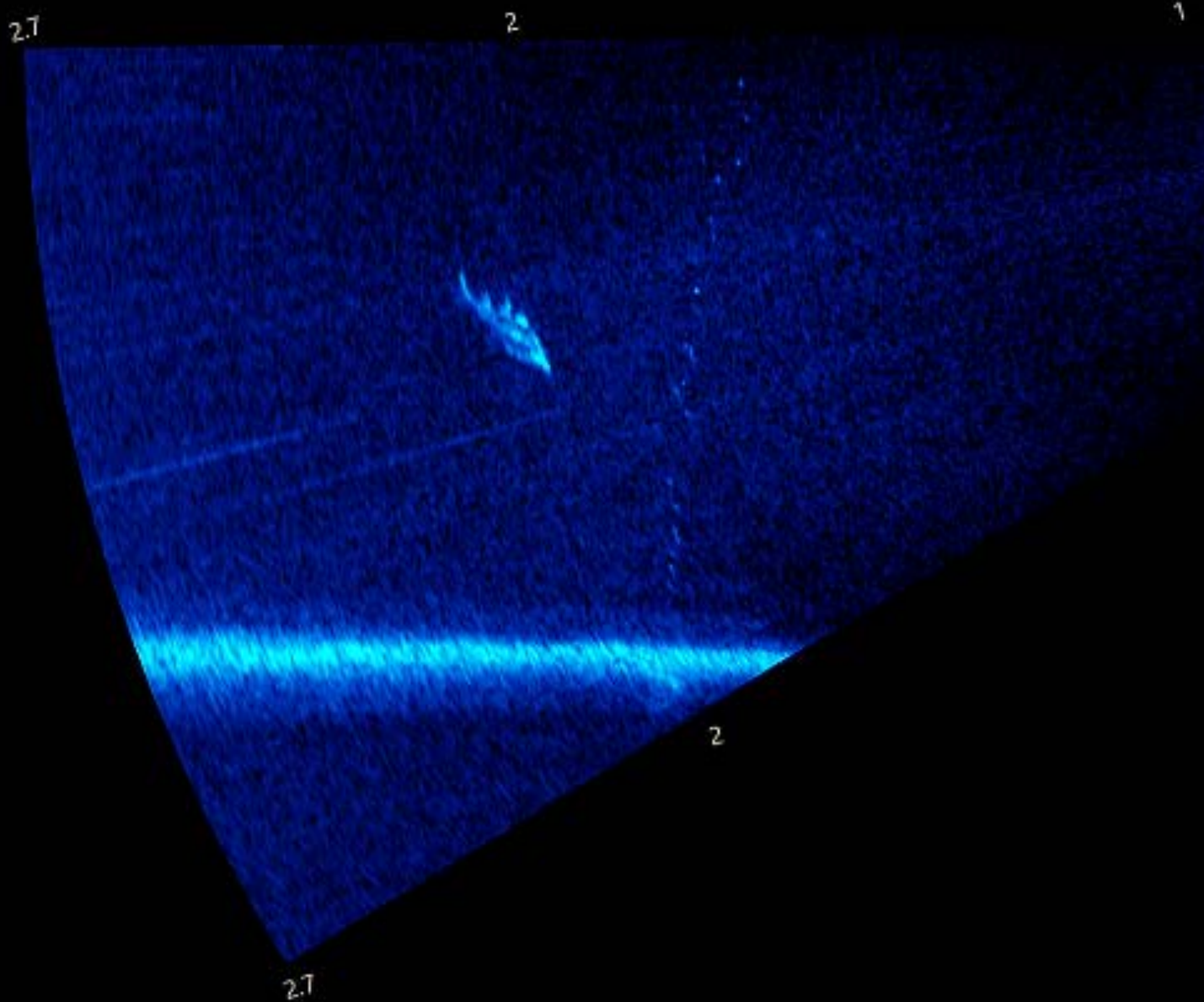
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1. General introduction and expedition goals

Helge Niemann, Chief Scientist

Methane (CH₄) is an important greenhouse gas, that is 32 times more potent than CO₂ on a time horizon of 100 years (Etminan et al., 2016). Though the half-life of atmospheric methane is relatively short (~ 9 years), CH₄ concentrations in the atmosphere have risen drastically to current values of ~ 1.9 ppm; i.e. ~ 2.5-fold higher compared to preindustrial values (IPCC, 2021). The exact mechanisms behind this increase are not fully understood, yet it is clear that the increase in the atmospheric methane budget is caused by anthropogenic sources (Nisbet et al., 2019; IPCC, 2021; Saunio et al., 2025); together, these amount to 345 - 409 Tg yr⁻¹. Natural CH₄ sources are overall on a similar scale contributing about 40% (195 - 457 Tg yr⁻¹) to the total atmospheric budget (540 – 865 Tg yr⁻¹).

Though it is likely that the overall contribution of the Ocean to the atmospheric methane budget is comparably small, ocean budget estimates vary considerably. Shelf seas for example are with 6 - 22 Tg yr⁻¹ the main contributor of natural oceanic methane emission to the atmosphere though the shelf only accounts for 8 - 10 % of the global ocean surface (Weber et al., 2019; Saunio et al., 2020). Compared to the open ocean, shelf seas are characterized by high nutrient loads, high primary production, high sedimentation rates and subsequent burial of dead organic matter to the seabed. This leads to elevated methane production in sediments by microbial or thermogenic processes (Reeburgh, 2007). Methane emission related to offshore industries on the other hand are not well constrained but expected to be substantial (Pühl et al., 2024; IEA, 2025). However, methane in shelf sea sediments is of commercial value and thus extracted. After exploitation, wells are sealed to prevent leakage, but recent investigations in the UK and German sector of the North Sea by Vielstädte et al. (2017), Böttner et al. (2020) and de Bruin (Bruin et al., 2025) however, found acoustic flares in the water column in vicinity of well heads; these acoustic features are caused by plumes of rising bubbles emanating from the sea floor. Such flares were almost always found when the well heads were in close vicinity to so-called bright spots in seismic data. Bright spots are caused by high amplitude response in sound velocity of the subsurface, e.g. triggered by the presence of shallow gas. The studies by Vielstädte et al. (2017), Böttner et al. (2020) could not fully clarify why the location of sea floor gas release was often at some distance from the well head (i.e. the leak-tightness of the well head seal itself was not necessarily compromised). However, the statistical co-occurrence of flares and (abandoned) wells suggested a causality. The available investigations also suggest that the frequency of plumes in UK and Norwegian sector might be higher than in the Dutch sector of the North Sea (Bruin et al., 2025).

The Dutch sector of the North Sea is rich in shallow and deep subsurface methane. The deep methane is extracted from multiple active wells and many more wells are abandoned and sealed. With respect to the previous findings (Vielstädte et al., 2017; Böttner et al., 2020; Bruin et al., 2025) this raises the questions:

- **if and how frequent gas release occurs at or in the vicinity of (abandoned) wells in the Dutch sector of the North Sea;**
- **if the gas release is caused by the previous drilling and/or inappropriate sealing attempts.**

Furthermore, leaking offshore wells, may form an anthropogenic analogue to natural cold seeps. At cold seeps, methane migrates upwards through cracks and fissures in the sea bed and may be released as dissolved or free gas into the water column (James et al., 2016). Cold seeps are thus methane hotspot point sources, and they occur frequently along shelf seas across the globe (Steinle et al., 2015), promoting methane transport to the atmosphere (McGinnis et al., 2006; Deimling et al., 2011).

Nevertheless, a substantial amount of the water column methane content at cold seeps is consumed by aerobic methane oxidizing bacteria (MOB) that mediate the aerobic oxidation of methane (MOx; Reeburgh 2007).

This raises a further question:

- **if and how much of the released CH₄ is microbially consumed in the water column and how much is ultimately released to the atmosphere.**

With these questions in mind, NIOZ & TNO have been commissioned by SoDM to investigate CH₄ dynamics at abandoned wells in the Dutch North Sea. In the first phase of this project, a first research expedition with R/V Pelagia was carried out in summer 2022 (June 2nd to 22nd (cruise PE-503). During this cruise, around 50 well locations were investigated for leakage and ranked for further in-depth investigation (Bruin et al., 2025). These investigations were aimed to take place during well mixed and fully stratified water column conditions, as this can severely influence methane release to the atmosphere (Steinle et al., 2016; Groot et al., 2024). An expedition in 2024 (PE-525) was thus conducted during fully mixed and quite stormy conditions.

The current cruise, PE-549, was carried out to further investigate the intermittency of seafloor methane release at the B17-05 and B17-04 sites visited during previous expeditions. In addition, we aimed to survey other suspended and abandoned well locations and assess potential methane emissions using echosounder-based techniques and direct observations with a remotely operated vehicle (ROV). We also tested new approaches for calibrating sonar-based methods to quantify methane release from the seafloor. Finally, we measured methane concentrations in the water column in situ using laser absorption spectrometry and/or collected discrete water samples for concentration and stable carbon isotope analysis.

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2. Geographical area

Helge Niemann, Chief Scientist

AI sampling during PE-549 was conducted in the North Sea, within the EEZ of the Netherlands (Figure 1). This region features several thermogenic gas fields but also pockets of shallow gas and gas is exploited from numerous wells (www.nlog.nl). Water depth in this area is mostly 20 - 45 m. In total we conducted 95 single stations. Sonar observations were conducted at 110 well surface locations, while ROV observations were focused on locations B17-05, B17-04, K06-01 and L08-P-01/02/03/05. A bubble generator was deployed at location B17-05 and close to K10-C-01 and E11-01. Of the 110 well locations, B17-01, B17-03, B17-04 and B17-05 were visited already in during previous cruises. A complete station list and a full list of the visited wells is presented in the appendix.

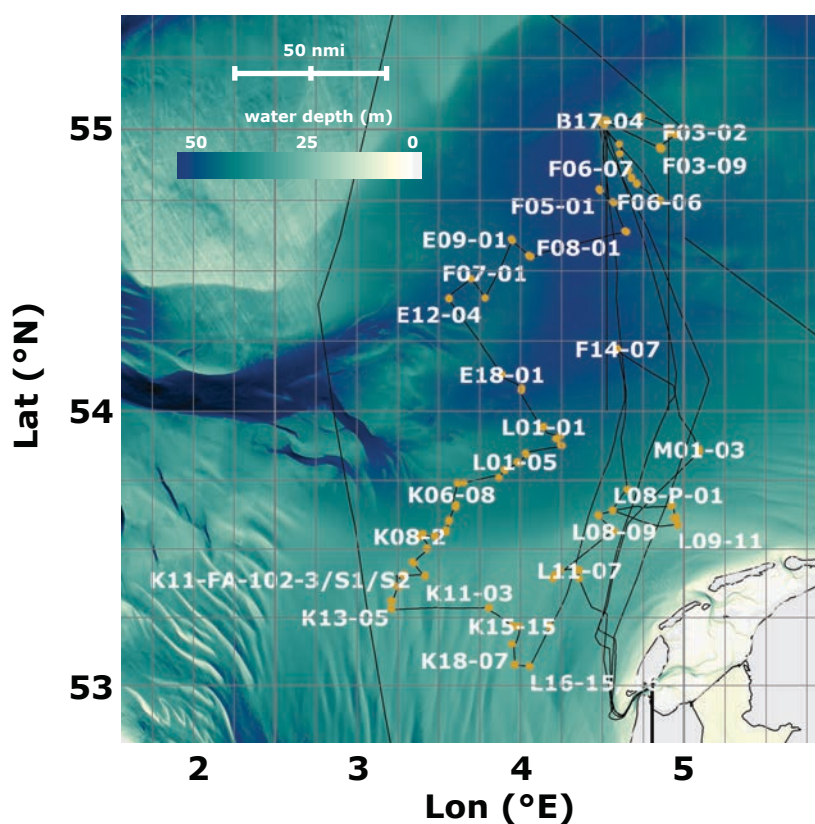


Figure 1 Area of investigation during PE-549. Single stations are highlighted as an orange dot, while the cruise track is indicated as a black line.

3. Bubbles in the water column

Rosanne Huybens, Laurens van der Marel, Martin Wilpshaar

3.1 Echosounder-based detection of bubbles

Both a single and a multi beam echo sounder were used to study the water column for methane bubbles rising from the seafloor and for seafloor features. On 114 locations the multibeam was used with a wide swath (detection mode) to detect bubbles. This was done by sailing parallel lines with a length of roughly 200 meters and distance between the lines that was roughly equal to the water depth. The goal was to measure an area of 200 by 250 meters with 50% overlap of the lines on both sides, as the side lobe image was not of high enough quality for bubble detection. With a water depth of 50 meters five lines were sailed in a 'paperclip', if the sea was significantly shallower one or two lines would be sailed extra. The sailing speed was aimed to be 2 knots to allow sufficient data points to be recorded within the water column needed for proper statistical analyses of the reflection strength.

When bubbles were suspected at a new location, more lines were sailed with the narrow swath multibeam (quantification mode) and the single beam was used, too. At locations where bubbles were found during previous methane expeditions, two other configurations of lines were sailed. Firstly, two boxes ($\sim 0.75 \times 0.75$ nmi) filled with lines were sailed over shallow gas leakage areas around (i) B17-03 and B17-05 as well as (ii) over B17-04. This was done to check how many plumes were active and at what locations compared to previous observations. Secondly, at B17-03, we sailed repeated lines over the location to investigate seepage intermittency.

3.1.1 Ships mounted single beam Echo sounder

The EK80 is a system consisting of one or multiple transducers with centre frequencies ranging from 18 to 333 kHz. For this study a mobile system, installed on the port side measurement pole of the vessel, was used consisting of a wide band transceiver (WBT mini) and two transducers with nominal frequencies of 70 and 200 kHz (Simrad ES70-7C and ES200-7C respectively). The ES70-7C is a split beam transducer with a bandwidth of 45-90 kHz and a circular beamwidth of 7 degrees. The ES200-7C also is a 7 degrees split beam transducer. The bandwidth for this device ranges from 160 to 260 kHz. Position and motion data is stored within the datafile. This information is supplied by the Seapath380/MRU 5+ ships attitude system. The position of the transducers on the pole relative to the GNSS antenna and MRU5+ is included in the final positioning of the data. Data were recorded using the matching Kongsberg EK80 software. The data was stored in raw format.

3.1.2 Ships mounted multi beam Echo sounder

All surveys were carried out with a high-resolution Kongsberg EM2040MKII mobile multibeam echosounder mounted on the ships port side measuring pole. The EM2040MKII is a high resolution 200-700 kHz shallow water multibeam. Experience during the 2022 cruise for this project has shown that running it at a frequency of 300 kHz gives the best possible results. Therefore, also this year surveys were carried out using 300 kHz. The beam opening angle at this frequency is 1° for the transmitter and receiver beam angle respectively. The swath opening angle during detection mode was fixed at 55° port side and starboard side. During quantitative mode the swath opening angle was set to 45° port side and starboard side. An offset calibration was carried out at the beginning of the cruise. However, since the pole did not return to exactly the same position at each deployment, this resulted in variable angular offsets for subsequent runs (i.e. a horizontal seabed appears to be dipping a couple of degrees). Therefore, a correction must be applied to the raw data post cruise.

During earlier cruises an equipment setup was used with the EM2040 connected to its own Kongsberg Seapath380 navigation and attitude processing unit with associated GNSS antennas and an MRU5+ motion reference unit mounted on the transducer pod. However, experience during these earlier cruises has shown that the vibration of the ship's deployment pole is too fast for the MRU to be able

to compensate for this motion. This resulted in a cascading of errors. Because of this, during the present cruise it was decided to use the ships Seapath380 in combination with a Kongsberg 3710 DGNSS receiver and ships MRU. Although in theory this would result in data not properly corrected for motion (the pole vibrations is not corrected for) in practice the data was of good enough quality since no accurate bathymetry was needed during this cruise and only water column backscatter data (with backscatter intensity as such being more important than the exact position at which this was measured) was aimed for.

The water column sound velocity profile was determined by means of SVP casts with an AML Oceanographic Base X2. A new cast was done in cases where the sound velocity measured by the sound velocity sensor positioned directly on the echosounder pole, was significantly deviating from the velocity used from the previous cast. The profile was processed with AML seacast software.

3.2 ROV mounted ARIS

(Rosanne Huybens, Laurens van der Marel, Martin Wilpshaar)

The ROV was equipped with an ARIS Explorer 3000 imaging sonar (Figure 2) produced by Sound Metrics. The two main aims of this instrument were 1) detecting the presence of gas seeps and help guiding the ROV towards the seep locations and 2) use the high-resolution images to determine bubble speed and bubble rate fluctuations order to quantify the volume of gas being released within a certain time period at these sites.

The ARIS 3000 Explorer is a high-resolution acoustic imaging instrument using a frequency of 1.8 MHz in detection mode and 3 MHz when in identification mode. The image is constructed from its 128 individual beams. During the cruise the high resolution 3 MHz identification mode was used. This resulted in high quality 'acoustic video' data. Because of the high frequency used, the range of the system is limited to about 5 metres in identification mode. However, since the acoustic signals were not hampered by the very high concentration of suspended material in the water column, limiting the optical visibility often to less than the length of the ROV manipulator arm, it was still possible to produce the needed high-resolution imagery. An example of the quality of the ARIS data can be seen in Figure 4.



Figure 2 The complete ARIS Explorer 3000 equipment. The underwater transducer unit is shown on the right hand side (size about 30x18x14 cm). Image by Sound Metrics.

When interpreting ARIS images, it needs to be considered that the sonar produces a two dimensional image of a three-dimensional world (Figure 3). In addition to this, because the positioning of the ROV relative to the seep site can be limited due to wave (shallow water and sometimes strong wave action during the cruise, waves can influence conditions at the seabed) and tidal current conditions it was not always possible to have an optimal orientation of the acoustic camera which could result in non-optimal imaging orientations. In addition to this, one has to realise that the 'viewing direction' of the camera is not the same as the viewing direction of the observer watching the screen (Figure 4).

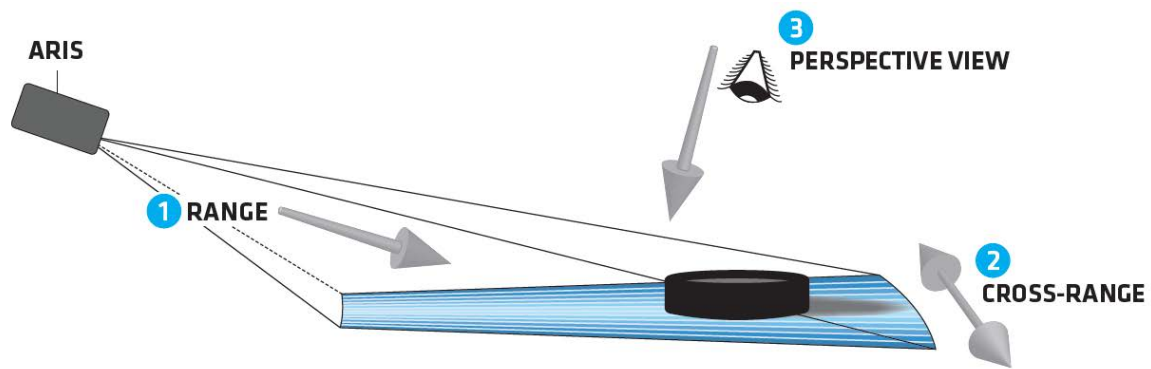


Figure 3 Image illustrating the viewing direction of the ARIS 3000 and the perspective view of the observer. Image by Sound Metrics.

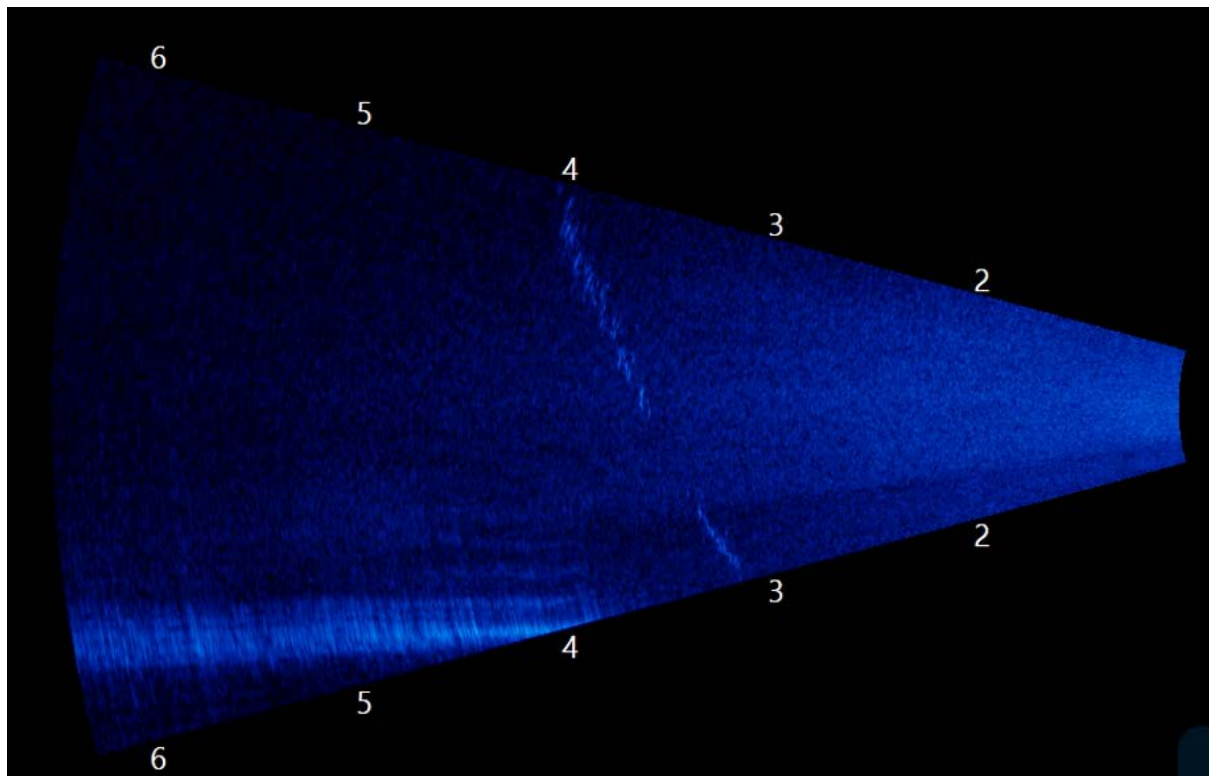


Figure 4 Screenshot of the ARIS 3000 as an example of the data quality produced by the system. An intermittent bubble stream can clearly be observed in the centre of the image. The seabed is represented by the bright blue horizontal line.

3.3 ROV mounted funnel

A small, 'handheld' funnel with an attached syringe (Figure 5) was in some cases attached to the ROV for dives (Figure 6). It was used when bubble plumes were located to measure the flux. To do so the ROV would fly to a bubble plume and put the funnel over the plume. By aiming the ROV's camera at the funnel the filling of the syringe could be watched. The times and volumes were noted on observation sheets to later calculate flux.



Figure 5 The funnel has a syringe attached on top to measure volumes.



Figure 6 ROV inside TMS on deck, funnel is mounted to arm on the right.

3.4 Bubble generator

To contribute to the knowledge of how to accurately quantify methane leakage acoustically, a series of experiments using a controlled gas leak at the seabed have been conducted. These experiments aimed to calibrate multibeam echosounder (MBES) signals against known gas release rates and were realised through the development of a custom bubble generator by the NIOZ workshop. The built bubble generator produced a steady stream of distinct air bubbles, while also allowing the release rate to be precisely controlled. With the addition of a sparger on top of the air outlet, the bubble size distribution of the released gas was adjusted in an attempt to achieve a consistent and predefined bubble size. Eventually, the bubble generator was equipped with a GoPro aimed at the sparger/ bubble release point as well.

When deployed successfully, the bubble generator was left on the seabed. Before every MBES operation both ARIS and ROV mounted funnel measurements were conducted, so that with every variation in flow rate setting both the bubble size and flow rate could be determined. As the location of the bubble generator was recorded during deployment, it was made sure that the Pelagia sailed directly over the generator during the multibeam echosounder operations.

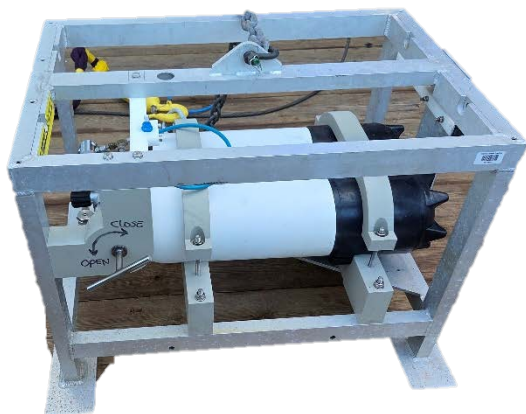


Figure 8 Bubble generator on deck, ready for deployment



Figure 7 ROV camera view of the bubble generator placed on the seabed. Flow rate measurement funnel is located in the right hand.

Within the study area, experiments with the bubble generator were conducted at three locations: at a depth of 30 meters, 46 meters and 43 meters. During the experiments at this last location, a leaking well was present, and its bubble plume could be investigated in combination with the bubble generator's plume.

In the end, 45 MBES measurement were recorded where bubble plumes could be seen clearly in the water column data. The returned acoustic signals obtained from these 45 measurements correspond to seven distinct flow rates. By systematically comparing these measured signals with the corresponding known gas release rates, a field-based calibration curve will be established. The established quantitative relationship enables more precise evaluation of uncertainties and sensitivities in current water column data-based gas flow estimations.

4. Dissolved Methane in the Water column

Annalisa Delre

4.1 In situ measurements

Along with the standard method consisting of sampling with Niskin bottles, a Methane Sensor Type LMS (Franatech GmbH, Germany, Figure 4.1) was used to measure dissolved methane concentration in the water column. The detection principle of this device is based on laser absorptiometry. Water is pumped across the laser cavities membrane with a Seabird 5M Titanium pump. The dissolved methane in the water diffuses through a silicon-rubber membrane into the measuring chamber. Absorption of laser light was then proportional to the mixing ratio of methane in the instrument's measuring chamber, which was in equilibrium with dissolved methane in the sea water. With the aid of a factory calibration, the mixing ratio in the cavity was corrected for the inertia of the silicon membrane, allowing to calculate water column methane concentration (Wiesenburg et al., 1979). The sensor was installed in the frame of the CTD carousel and measured during each cast. The same sensor was installed on the mini-lander frame (see respective section in the cruise report).

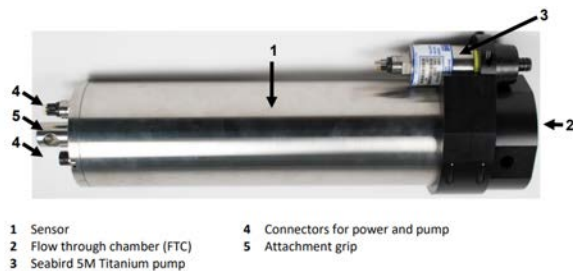


Figure 4.1 The Methane Sensor.

4.2 Discrete water samples

We performed casts with a conductivity-temperature-depth (CTD) probe at two interesting locations (station 28 and 91). Considering the water column well mixed, we decided to collect distinct samples at 3 depth: bottom, middle and surface. Dissolved methane concentrations were determined using a headspace (HS) technique (Green, 2005). As soon as CTD was in the deck, 260 ml glass serum bottles were filled in triplicates from the Niskin bottles, closed with black-butyl rubber stoppers (Rubber B.V., the Netherlands) and crimped top-sealed. Subsequently, 10ml N₂ was added to create a headspace and we fixed the sample with 5ml NaOH solution (25% w/v). The methane concentrations in the headspace will be measured in our home laboratory with a gas-chromatograph (Thermo Scientific FOCUS GC equipped with a Restek stainless steel column HayeSep-Q, 80/100, General configuration (length 2 m, 2 mm i.d., 1/8 in. o.d.) with flame ionization detection.

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5. Autonomous lander systems for long-term monitoring

Two autonomous landers were used during the cruise to measure at bubble plumes for a prolonged period. The Mini-lander (or M-lander) was deployed for two days while the Funnel Lander (or F-lander) was deployed as long as possible to cover multiple tidal cycles and natural variances in methane flux. The F-lander was used to catch bubbles and measure fluxes, while the Mini-lander was used to measure multiple parameters.

5.1 Mini-Lander

Annalisa Delre, Rosanne Huybens

An autonomous lander frame was developed by NIOZ that was equipped with multiple to enable long-term timelapse measurements and recordings. For the PE-537 cruise an M-lander was developed (Figure 9). The reason to do so was that it proved to be difficult to accurately place the previously used Albex lander, while the M-lander could be dragged in place by the ROV. The lander was equipped with a laser absorption spectrometer to measure the amount of dissolved methane in the water, a doppler current profiler, hydrophone and a CTD sensor (Conductivity, Temperature, Depth) (Table 1). The spectrometer was powered by a 15V battery-pack that was attached to the lander. The rest of the sensors were powered by internal batteries.

During the PE-549 cruise the M-lander was deployed one time at one locations, namely at a natural seepage location near well B17-04. Before lander deployment, the bubble plume locations were determined with the multibeam. Based on the plume locations, the lander was deployed as close as possible with respect to the bubble plumes and dragged in its final position by the ROV. After deployment of two days, the lander was retrieved and the data from each sensor was collected.



Figure 9 Mini-lander on deck

Table 1 Equipment mounted to the mini-lander with the used configurations during PE-549

Equipment	Model	Serial number	Software
Current profiler	Nortek Aquadopp current profiler	05-10618	Aquapro V20.00.02
Hydrophone	icListen 200 SC2-ETH	6083	Lucy
Laser spectrometer	Franatech	05-10618	Franatech Datalogger Support
CTD	Microcat CTD SBE37	5389	Sea Term V1.59

5.1.1 Current profiler (Aquapro)

The Nortek Aquadopp current profiler (Aquapro) measures current speed and direction in multiple layers, or vertical cells, through the water column. The idea of vertical cells is that the currents vary little in the horizontal plane, but may differ more in vertical layers due to for instance the tidal cycles. An acoustic Doppler instrument transmits a short pulse of sound (“ping”) of constant frequency into the water, listens to its echo and measures the change in pitch or frequency of the echo caused by the doppler effect. The temperature is measured by a thermistor embedded in the head and reported in degrees Celsius. This information is of vital importance, since the instrument uses the speed of sound to convert time to distance, and the speed of sound depends on temperature. Furthermore, the hydrostatic pressure is measured with the pressure sensor and reports in units of dbar.

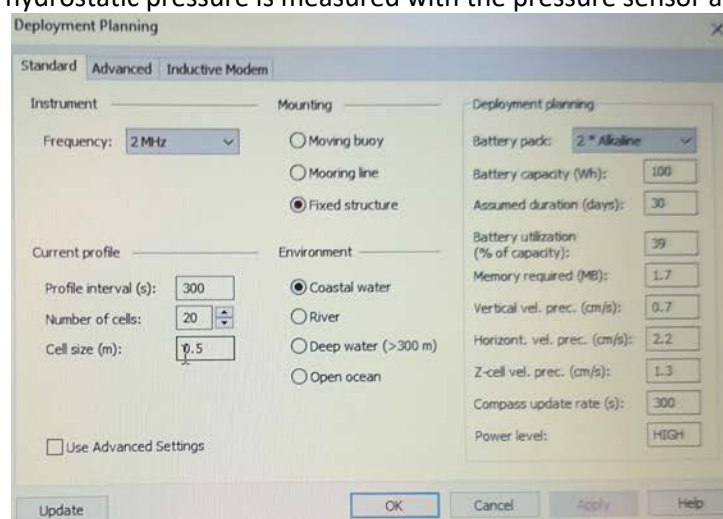


Figure 10 Settings of the Aquadopp current profiler

During PE-549, the current profiler was mounted on the lander with the transducer head facing upward and level with the top of the frame, so that it has an unobstructed ‘view’ into the overlying water column. During the deployment of the lander, every 5 minutes the current and direction was measured over 20 cells of each 0.5 m, covering a water column of 10 m. Also, the pressure and temperature at the instrument was measured every 5 minutes.

5.1.2 Hydrophone

A hydrophone (Figure 11) was used to record the sound of the bubbles. The goal of these recordings is to relate sound to the number of bubbles in the water column. Sound is recorded continuously. The hydrophone was added to the lander last minute. Therefore, it was not possible to also install the 24V battery pack that was needed to record during the whole deployment. The internal battery powered measurements for roughly eleven hours.

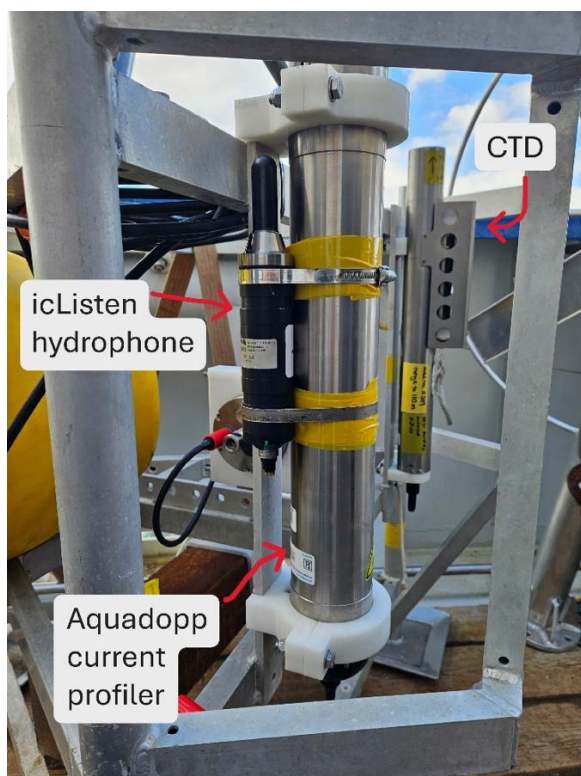


Figure 11 Mini-lander with hydrophone, Aquadopp and CTD mounted to it.

5.1.3 Laser spectrometer

A Methane Sensor Type LMS (Franatech GmbH, Germany, Figure 11) was attached to the lander frame (see section 4). The LMS was preprogrammed to sample every 30 seconds.

5.1.4 CTD (MicroCAT)

The SBE 37-SM MicroCAT (CTD) (Figure 12) is a sensor that measures water parameters in one location over an extended period to produce a time-series of data. It measures the Conductivity (S/m), Temperature (°C) and pressure (dbar), from which the variable salinity and sound velocity of the seawater can be derived. During the PE-549 expedition the MicroCAT was fixed vertically in the top part of the lander. During deployment every 5 minutes the conductivity, temperature and pressure were measured and from which salinity was derived.



Figure 12 CTD MicroCAT

5.2 F-Lander

Rosanne Huybens

The Funnel Lander (F-Lander; Figure 13) is a lander that was developed for expedition PE537 and consists of a large funnel (1,5 by 1,5 m) that catches bubbles and guides them into a measuring chamber. One adjustment was made relative to the PE537 expedition, namely the sensors were replaced to optical sensors that notice the light refraction difference between seawater and gas. The

time it takes to fill the chamber is measured. The measuring chamber is 4661.67 ml in volume and when it is full, the captured gas is automatically released, and the time of release is recorded. From this we can compute the flux in ml per second. Secondly, the lander is equipped with a MicroCAT CTD (similar to the one on the m-lander, with S/N 26615). The CTD records conductivity, depth and temperature, and this allows for conversion of the measured volume into moles and grams (using the formula $pV = nRT$). This results in a flux in gram per second.

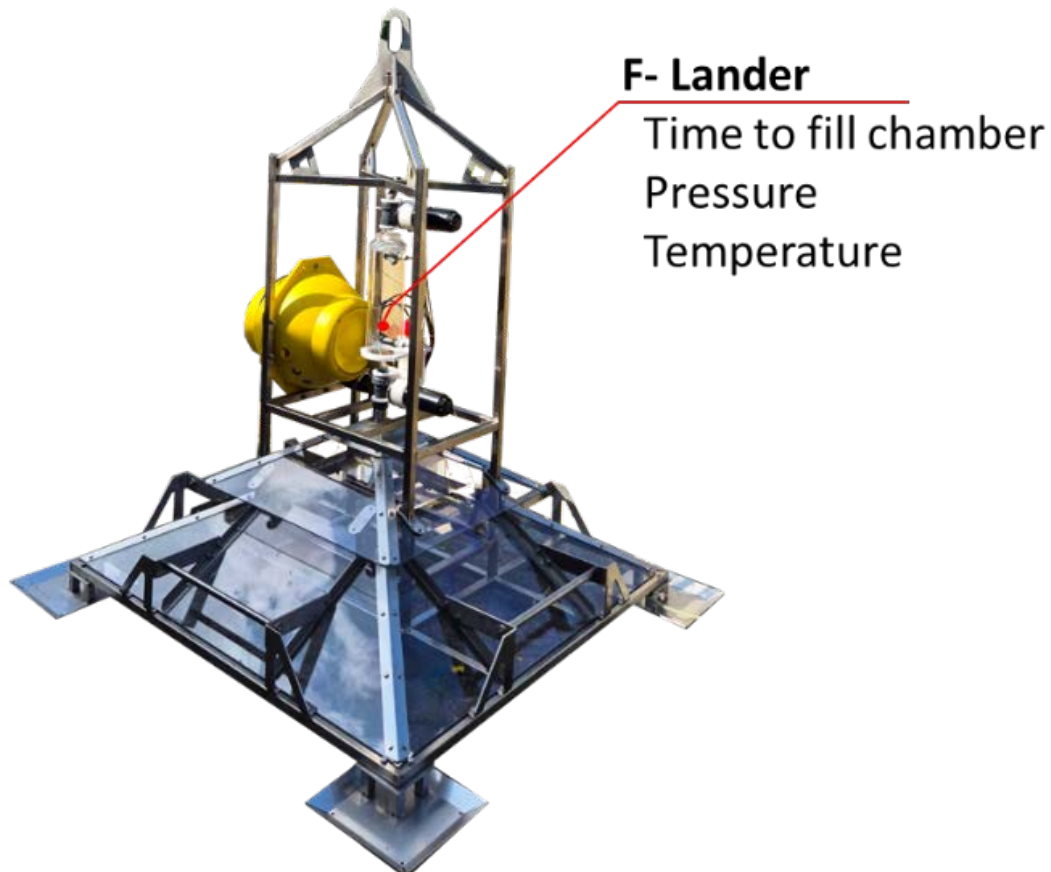


Figure 13 The funnel lander

Appendix I Station list

<i>Date</i>	<i>latitude</i>	<i>longitude</i>	<i>Phase name</i>	<i>Device name</i>	<i>Action name</i>	<i>Operation Id</i>	<i>Cast</i>	<i>Location</i>
22/09/2025 11:45	52.9958	4.7952	None 0	None	CRUISE START	64PE549	None	Marsdiep
23/09/2025 09:36	55.0318	4.4833	STATION 2	Multibeam	BEGIN	64PE549EM3022	2_1	B17-04
23/09/2025 10:15	55.0363	4.4808	TRANSIT 3	Multibeam	END	64PE549EM3022	2_1	
23/09/2025 14:59	55.0117	4.5108	STATION 3	ROV deployment	FAIL	64PE549ROVDEP3	3_1	
23/09/2025 17:12	54.746	4.8485	STATION 4	SVP	BEGIN	64PE5494	4_1	F06-06
23/09/2025 17:40	54.7448	4.8482	STATION 5	Multibeam	BEGIN	64PE549EM3025	5_1	
23/09/2025 18:48	54.7513	4.8542	STATION 5	Multibeam	END	64PE549EM3025	5_1	
23/09/2025 19:52	54.8082	4.7102	STATION 6	SVP	END	64PE5496	6_1	F06-07
23/09/2025 19:59	54.8065	4.7102	STATION 7	Multibeam	BEGIN	64PE549EM3027	7_1	
23/09/2025 21:14	54.8107	4.7108	STATION 7	Multibeam	END	64PE549EM3027	7_1	
23/09/2025 22:09	54.827	4.6772	STATION 8	Multibeam	BEGIN	64PE549EM3028	8_1	F06-01
23/09/2025 23:24	54.8307	4.6792	STATION 8	Multibeam	END	64PE549EM3028	8_1	
24/09/2025 00:16	54.853	4.6557	STATION 9	Multibeam	BEGIN	64PE549EM3029	9_1	F02-01
24/09/2025 01:45	54.8575	4.6593	STATION 9	Multibeam	END	64PE549EM3029	9_1	

24/09/2025 02:30	54.9142	4.6072	STATION 10	Multibeam	BEGIN	64PE549EM30210	10_1	F02-07
24/09/2025 04:07	54.9482	4.603	STATION 10	Multibeam	END	64PE549EM30210	10_1	
24/09/2025 06:07	55.0335	4.4813	STATION 11	ROV deployment	BEGIN	64PE549ROVDEP11	11_2	B17-04
025-09-24 08:14:56	55.034	4.4803	STATION 11	Mini Lander	END	64PE54911	11_1	
24/09/2025 08:14	55.034	4.4803	STATION 11	ROV deployment	END	64PE549ROVDEP11	11_2	
24/09/2025 11:27	54.9313	4.8625	STATION 12	SVP	END	64PE54912	12_2	F03-09
24/09/2025 11:04	54.9327	4.855	STATION 12	Multibeam	BEGIN	64PE549EM30212	12_1	
24/09/2025 13:11	54.9323	4.8633	STATION 12	Multibeam	END	64PE549EM30212	12_1	
24/09/2025 13:25	54.9358	4.8615	STATION 13	Multibeam	BEGIN	64PE549EM30213	13_1	F03-02
24/09/2025 14:44	54.9377	4.85	STATION 13	Multibeam	END	64PE549EM30213	13_1	
24/09/2025 14:44	54.9377	4.85	TRANSIT 14	ROV deployment	BEGIN	64PE549ROVDEP13	13_2	
24/09/2025 15:18	54.9375	4.851	TRANSIT 14	ROV deployment	END	64PE549ROVDEP13	13_2	
24/09/2025 15:54	54.9805	4.9452	STATION 14	Multibeam	BEGIN	64PE549EM30214	14_1	F03-07
24/09/2025 16:49	54.9818	4.9523	STATION 14	Multibeam	END	64PE549EM30214	14_1	
24/09/2025 17:23	54.9858	4.9023	STATION 15	Multibeam	BEGIN	64PE549EM30215	15_1	F03-FA-01
24/09/2025 18:02	54.9868	4.903	STATION 15	Multibeam	END	64PE549EM30215	15_1	
24/09/2025 18:15	54.9917	4.8997	STATION 16	Multibeam	BEGIN	64PE549EM30216	16_1	F03-08
24/09/2025 19:08	54.993	4.9052	STATION 16	Multibeam	END	64PE549EM30216	16_1	

24/09/2025 19:29	54.9923	4.8992	STATION 17	Multibeam	BEGIN	64PE549EM30217	17_1	F03-01
24/09/2025 20:36	55.0013	4.904	STATION 17	Multibeam	END	64PE549EM30217	17_1	
24/09/2025 20:39	55.0025	4.903	STATION 18	Multibeam	BEGIN	64PE549EM30218	18_1	B18-03
24/09/2025 21:37	55.0058	4.9112	STATION 18	Multibeam	END	64PE549EM30218	18_1	
24/09/2025 22:56	55.0452	4.7267	STATION 19	Multibeam	BEGIN	64PE549EM30219	19_1	B18-06
25/09/2025 00:26	55.0448	4.7388	STATION 19	Multibeam	END	64PE549EM30219	19_1	
25/09/2025 01:51	55.0217	4.5095	STATION 20	Multibeam	BEGIN	64PE549EM30220	20_1	B17-03 → B17-05
25/09/2025 03:48	55.0295	4.5255	STATION 20	Multibeam	END	64PE549EM30220	20_1	
25/09/2025 06:06	55.0347	4.4767	STATION 21	SVP	BEGIN	64PE54921	21_1	B17-04
25/09/2025 06:11	55.0345	4.4777	STATION 21	SVP	END	64PE54921	21_1	
25/09/2025 06:20	55.034	4.4762	STATION 21	Multibeam	BEGIN	64PE549EM30221	21_2	
25/09/2025 08:14	55.035	4.4867	STATION 21	Multibeam	END	64PE549EM30221	21_2	
25/09/2025 08:55	55.0303	4.5228	STATION 22	ROV deployment	BEGIN	64PE549ROVDEP22	22_1	B17-05
25/09/2025 13:24	55.0312	4.5232	STATION 22	Funnel Lander	END	64PE54922	22_2	
25/09/2025 13:44	55.0313	4.5232	STATION 22	ROV deployment	END	64PE549ROVDEP22	22_1	
25/09/2025 15:10	55.0337	4.4828	STATION 23	ROV deployment	BEGIN	64PE549ROVDEP23	23_1	B17-04
25/09/2025 15:15	55.0337	4.4843	STATION 23	ROV deployment	END	64PE549ROVDEP23	23_1	
25/09/2025 15:34	55.0335	4.4903	STATION 24	Multibeam	BEGIN	64PE549EM30224	24_1	B17-04 box

25/09/2025 23:45	55.0407	4.4955	STATION 24	Multibeam	END	64PE549EM30224	24_1
26/09/2025 00:28	55.0247	4.5092	STATION 25	Multibeam	BEGIN	64PE549EM30225	25_1
26/09/2025 01:25	55.0222	4.5168	STATION 25	Multibeam	END	64PE549EM30225	25_1
26/09/2025 06:40	55.0198	4.5063	STATION 26	SVP	BEGIN	64PE54926	26_1
26/09/2025 06:41	55.02	4.5062	STATION 26	SVP	END	64PE54926	26_1
26/09/2025 13:45	55.0335	4.4805	STATION 27	Mini Lander CTD with	RECOVER	64PE54927	27_1
26/09/2025 14:39	55.0335	4.4805	STATION 28	Samples	BOT	64PE549CTDBOT28	28_1
26/09/2025 17:26	55.0272	4.5305	STATION 29	Multibeam	BEGIN	64PE549EM30229	29_1
26/09/2025 20:58	55.0327	4.514	STATION 29	Multibeam	END	64PE549EM30229	29_1
26/09/2025 21:35	55.024	4.4963	STATION 30	Multibeam	BEGIN	64PE549EM30230	30_1
27/09/2025 05:46	55.0305	4.5218	STATION 30	Multibeam	END	64PE549EM30230	30_1
27/09/2025 07:58	55.0305	4.5228	STATION 32	F lander salvage	BEGIN	64PE54932	32_3
27/09/2025 12:07	55.0313	4.5233	STATION 32	F lander salvage	END	64PE54932	32_3
27/09/2025 14:58	54.7893	4.481	TRANSIT 34	SVP	END	64PE54932	32_4
27/09/2025 14:59	54.7895	4.4808	TRANSIT 35	Multibeam	BEGIN	64PE549EM30233	33_1
27/09/2025 15:48	54.7838	4.4882	TRANSIT 35	Multibeam	END	64PE549EM30233	33_1
27/09/2025 16:37	54.745	4.5642	TRANSIT 36	Multibeam	BEGIN	64PE549EM30234	34_1

B17-03

B1705 box

B17-04

B17-05

B17-03

F05-01

F05-04

27/09/2025 17:16	54.7415	4.5717	TRANSIT 36	Multibeam	END	64PE549EM30234	34_1
27/09/2025 18:15	54.6417	4.6378	STATION 35	Multibeam	BEGIN	64PE549EM30235	35_1
27/09/2025 19:06	54.638	4.6482	STATION 35	Multibeam	END	64PE549EM30235	35_1
27/09/2025 21:55	54.5508	4.0637	STATION 37	SVP	END	64PE54937	37_1
27/09/2025 22:22	54.5512	4.054	STATION 37	Multibeam	BEGIN	64PE549EM30237	37_2
27/09/2025 23:26	54.555	4.0497	STATION 37	Multibeam	END	64PE549EM30237	37_2
28/09/2025 00:15	54.6125	3.9447	STATION 38	Multibeam	BEGIN	64PE549EM30238	38_1
28/09/2025 01:31	54.6073	3.9507	STATION 38	Multibeam	END	64PE549EM30238	38_1
28/09/2025 03:12	54.403	3.7842	STATION 39	SVP	END	64PE54939	39_1
28/09/2025 03:24	54.4028	3.7835	STATION 40	Multibeam	BEGIN	64PE549EM30240	40_1
28/09/2025 05:36	54.4718	3.6968	STATION 41	Multibeam	END	64PE549EM30240	40_1
28/09/2025 06:34	54.4015	3.5627	STATION 42	Multibeam	BEGIN	64PE549EM30242	42_1
28/09/2025 06:38	54.3995	3.5642	STATION 42	Multibeam	END	64PE549EM30242	42_1
28/09/2025 07:20	54.4018	3.5625	STATION 42	Bubble generator	BEGIN	64PE54942	42_4
28/09/2025 08:47	54.401	3.5628	STATION 42	Multibeam	BEGIN	64PE549EM30242	42_5
28/09/2025 12:03	54.4022	3.5625	STATION 42	ROV deployment	DEP	64PE549ROVDEP42	42_6
28/09/2025 14:08	54.403	3.565	STATION 42	Multibeam	BEGIN	64PE549EM30242	42_7

F08-01

F07-01

E09-01

E12-04

E12-03

E11-01

close to E11-01

28/09/2025 20:02	54.1295	3.887	STATION 43	Multibeam	BEGIN	64PE549EM30243	43_2	E18-01
28/09/2025 20:58	54.125	3.8823	STATION 43	Multibeam	END	64PE549EM30243	43_2	
28/09/2025 21:42	54.0802	4.007	STATION 44	Multibeam	BEGIN	64PE549EM30244	44_1	F16-05
28/09/2025 22:57	54.0738	4.0062	STATION 44	Multibeam	END	64PE549EM30244	44_1	
29/09/2025 00:16	53.9448	4.1417	STATION 45	Multibeam	BEGIN	64PE549EM30245	45_1	L01-01
29/09/2025 01:30	53.9412	4.1383	STATION 45	Multibeam	END	64PE549EM30245	45_1	
29/09/2025 02:17	53.9103	4.2468	STATION 46	SVP	END	64PE54946	46_1	L01-03
29/09/2025 02:17	53.9103	4.2468	STATION 47	Multibeam	BEGIN	64PE549EM30247	47_1	
29/09/2025 03:28	53.9008	4.2182	STATION 47	Multibeam	END	64PE549EM30247	47_1	
29/09/2025 03:29	53.9005	4.2167	STATION 48	Multibeam	BEGIN	64PE549EM30248	48_1	L01-02
29/09/2025 04:05	53.8993	4.2235	STATION 48	Multibeam	END	64PE549EM30248	48_1	
29/09/2025 04:45	53.8758	4.2472	STATION 49	Multibeam	BEGIN	64PE549EM30249	49_1	L01-05
29/09/2025 05:23	53.8752	4.2535	STATION 49	Multibeam	END	64PE549EM30249	49_1	
29/09/2025 06:25	53.8485	4.0313	STATION 50	SVP	END	64PE54950	50_1	L01-04
29/09/2025 07:24	53.8433	4.0345	STATION 50	Multibeam	BEGIN	64PE549EM30250	50_2	
29/09/2025 07:24	53.8433	4.0345	STATION 50	Multibeam	END	64PE549EM30250	50_2	
29/09/2025 07:56	53.8115	3.9952	STATION 51	Multibeam	BEGIN	64PE549EM30251	51_1	K06-01
29/09/2025 09:58	53.8168	3.9828	STATION 51	Multibeam	END	64PE549EM30251	51_1	

29/09/2025 10:07	53.8165	3.9823	STATION 51	ROV deployment	DEP	64PE549ROVDEP51	51_2
29/09/2025 10:34	53.8163	3.9808	STATION 51	ROV deployment	END	64PE549ROVDEP51	51_2
29/09/2025 11:20	53.8152	3.9847	STATION 51	ROV deployment	DEP	64PE549ROVDEP51	51_3
29/09/2025 11:39	53.8152	3.9847	STATION 51	ROV deployment	END	64PE549ROVDEP51	51_3
29/09/2025 12:16	53.786	3.9063	STATION 52	Multibeam	BEGIN	64PE549EM30252	52_1
29/09/2025 13:10	53.7895	3.9013	STATION 52	Multibeam	END	64PE549EM30252	52_1
29/09/2025 13:43	53.7582	3.8692	STATION 53	SVP	END	64PE54953	53_1
29/09/2025 13:48	53.7585	3.869	STATION 53	Multibeam	BEGIN	64PE549EM30253	53_2
29/09/2025 15:30	53.741	3.6553	STATION 53	Multibeam	END	64PE549EM30253	53_2
29/09/2025 15:45	53.7382	3.6167	STATION 54	Multibeam	BEGIN	64PE549EM30254	54_1
29/09/2025 16:35	53.7417	3.6155	STATION 54	Multibeam	END	64PE549EM30254	54_1
29/09/2025 17:17	53.6522	3.6032	STATION 55	Multibeam	BEGIN	64PE549EM30255	55_1
29/09/2025 18:09	53.6607	3.6047	TRANSIT 57	Multibeam	END	64PE549EM30255	55_1
29/09/2025 18:47	53.6048	3.5648	STATION 56	Multibeam	BEGIN	64PE549EM30256	56_1
29/09/2025 19:32	53.6008	3.5632	STATION 56	Multibeam	END	64PE549EM30256	56_1
29/09/2025 19:56	53.5692	3.5457	STATION 57	Multibeam	BEGIN	64PE549EM30257	57_1
29/09/2025 20:51	53.562	3.5447	STATION 57	Multibeam	END	64PE549EM30257	57_1
29/09/2025 21:34	53.5465	3.4775	STATION 58	Multibeam	BEGIN	64PE549EM30258	58_2

K06-06

K06-08

K05-F-02, K05-F-03, K05-11

K08-14

K08-2

K08-15

K08-07

29/09/2025 22:20	53.5468	3.4738	STATION 58	Multibeam	END	64PE549EM30258	58_2	
29/09/2025 23:00	53.5448	3.3907	STATION 59	Multibeam	BEGIN	64PE549EM30259	59_1	K08-08
30/09/2025 00:04	53.5503	3.3903	STATION 59	Multibeam	END	64PE549EM30259	59_1	
30/09/2025 00:15	53.5513	3.4028	STATION 60	Multibeam	BEGIN	64PE549EM30260	60_1	K08-01
30/09/2025 01:11	53.5553	3.4048	STATION 60	Multibeam	END	64PE549EM30260	60_1	
30/09/2025 01:55	53.5033	3.43	STATION 61	Multibeam	BEGIN	64PE549EM30261	61_1	K08-03
30/09/2025 02:38	53.4998	3.428	TRANSIT 63	Multibeam	END	64PE549EM30261	61_1	
30/09/2025 03:16	53.4472	3.3487	STATION 62	Multibeam	BEGIN	64PE549EM30262	62_1	K11-02, K11-FA-101, K11-FA-102, K11-FA-103
30/09/2025 04:30	53.454	3.3402	STATION 62	Multibeam	END	64PE549EM30262	62_1	
30/09/2025 05:07	53.3995	3.417	STATION 63	Multibeam	BEGIN	64PE549EM30263	63_1	K11-03
30/09/2025 05:42	53.4035	3.4182	STATION 63	Multibeam	END	64PE549EM30263	63_1	
30/09/2025 06:26	53.4022	3.2837	STATION 64	SVP	END	64PE54964	64_1	
30/09/2025 06:51	53.4007	3.287	STATION 64	Multibeam	BEGIN	64PE549EM30264	64_2	K10-C-01, K10-C-02, K10-C-03, K10-C-04
30/09/2025 07:42	53.408	3.2873	STATION 64	Multibeam	END	64PE549EM30264	64_2	
30/09/2025 10:24	53.408	3.2875	STATION 65	ROV deployment	REC	64PE549ROVDEP65	65_1	close to K10-C01
30/09/2025 07:54	53.408	3.2873	STATION 65	Bubble generator	BEGIN	64PE54965	65_2	
30/09/2025 11:09	53.408	3.2892	STATION 65	Multibeam	BEGIN	64PE549EM30265	65_4	
30/09/2025 12:04	53.4083	3.2873	STATION 65	Multibeam	END	64PE549EM30265	65_4	

30/09/2025 14:07	53.4082	3.2872	STATION 65	Bubble generator	BEGIN	64PE54965	65_6
30/09/2025 14:34	53.4075	3.2872	STATION 65	Multibeam	BEGIN	64PE549EM30265	65_7
30/09/2025 14:55	53.4082	3.2875	STATION 65	Multibeam	END	64PE549EM30265	65_7
30/09/2025 15:46	53.4083	3.2872	STATION 65	Bubble generator	END	64PE54965	65_6
30/09/2025 20:59	53.3628	3.2478	STATION 66	SVP	BEGIN	64PE54966	66_1
30/09/2025 21:23	53.3613	3.2565	STATION 66	Multibeam	BEGIN	64PE549EM30266	66_2
30/09/2025 22:13	53.3625	3.2498	STATION 66	Multibeam	END	64PE549EM30266	66_2
30/09/2025 22:56	53.3092	3.2172	STATION 67	Multibeam	BEGIN	64PE549EM30267	67_1
30/09/2025 23:58	53.31	3.2103	STATION 67	Multibeam	END	64PE549EM30267	67_1
01/10/2025 00:37	53.2823	3.21	STATION 68	Multibeam	BEGIN	64PE549EM30268	68_1
01/10/2025 01:23	53.2795	3.2133	STATION 68	Multibeam	END	64PE549EM30268	68_1
01/10/2025 03:53	53.2863	3.8095	TRANSIT 70	SVP	END	64PE54968	68_2
01/10/2025 03:54	53.2862	3.8095	STATION 69	Multibeam	BEGIN	64PE549EM30269	69_1
01/10/2025 04:46	53.283	3.8065	STATION 69	Multibeam	END	64PE549EM30269	69_1
01/10/2025 05:39	53.2185	3.9483	STATION 70	Multibeam	BEGIN	64PE549EM30270	70_1
01/10/2025 06:53	53.2165	3.9712	STATION 70	Multibeam	END	64PE549EM30270	70_1
01/10/2025 07:13	53.2168	3.9902	STATION 71	Multibeam	BEGIN	64PE549EM30271	71_1
01/10/2025 08:10	53.2172	3.9928	STATION 71	Multibeam	END	64PE549EM30271	71_1

K10-B-01, K10-B-02, K10-B-03, K10-B-04, K10-B-05, K10-B-06, K10-B-07, K10-B-08, K10-B-09, K10-B-10, K10-B-11, K10-B-12, K10-B-13, K10-B-14, K10-B-15, K10-B-16, K10-B-17, K10-B-18, K10-B-19, K10-B-20, K10-B-21, K10-B-22, K10-B-23, K10-B-24, K10-B-25, K10-B-26, K10-B-27, K10-B-28, K10-B-29, K10-B-30, K10-B-31, K10-B-32, K10-B-33, K10-B-34, K10-B-35, K10-B-36, K10-B-37, K10-B-38, K10-B-39, K10-B-40, K10-B-41, K10-B-42, K10-B-43, K10-B-44, K10-B-45, K10-B-46, K10-B-47, K10-B-48, K10-B-49, K10-B-50, K10-B-51, K10-B-52, K10-B-53, K10-B-54, K10-B-55, K10-B-56, K10-B-57, K10-B-58, K10-B-59, K10-B-60, K10-B-61, K10-B-62, K10-B-63, K10-B-64, K10-B-65, K10-B-66, K10-B-67, K10-B-68, K10-B-69, K10-B-70, K10-B-71, K10-B-72, K10-B-73, K10-B-74, K10-B-75, K10-B-76, K10-B-77, K10-B-78, K10-B-79, K10-B-80, K10-B-81, K10-B-82, K10-B-83, K10-B-84, K10-B-85, K10-B-86, K10-B-87, K10-B-88, K10-B-89, K10-B-90, K10-B-91, K10-B-92, K10-B-93, K10-B-94, K10-B-95, K10-B-96, K10-B-97, K10-B-98, K10-B-99, K10-B-100

K13-CF-01, K13-CF-02, K13-CF-03, K13-CF-04, K13-CF-05, K13-CF-06, K13-CF-07, K13-CF-08, K13-CF-09, K13-CF-10, K13-CF-11, K13-CF-12, K13-CF-13, K13-CF-14, K13-CF-15, K13-CF-16, K13-CF-17, K13-CF-18, K13-CF-19, K13-CF-20, K13-CF-21, K13-CF-22, K13-CF-23, K13-CF-24, K13-CF-25, K13-CF-26, K13-CF-27, K13-CF-28, K13-CF-29, K13-CF-30, K13-CF-31, K13-CF-32, K13-CF-33, K13-CF-34, K13-CF-35, K13-CF-36, K13-CF-37, K13-CF-38, K13-CF-39, K13-CF-40, K13-CF-41, K13-CF-42, K13-CF-43, K13-CF-44, K13-CF-45, K13-CF-46, K13-CF-47, K13-CF-48, K13-CF-49, K13-CF-50, K13-CF-51, K13-CF-52, K13-CF-53, K13-CF-54, K13-CF-55, K13-CF-56, K13-CF-57, K13-CF-58, K13-CF-59, K13-CF-60, K13-CF-61, K13-CF-62, K13-CF-63, K13-CF-64, K13-CF-65, K13-CF-66, K13-CF-67, K13-CF-68, K13-CF-69, K13-CF-70, K13-CF-71, K13-CF-72, K13-CF-73, K13-CF-74, K13-CF-75, K13-CF-76, K13-CF-77, K13-CF-78, K13-CF-79, K13-CF-80, K13-CF-81, K13-CF-82, K13-CF-83, K13-CF-84, K13-CF-85, K13-CF-86, K13-CF-87, K13-CF-88, K13-CF-89, K13-CF-90, K13-CF-91, K13-CF-92, K13-CF-93, K13-CF-94, K13-CF-95, K13-CF-96, K13-CF-97, K13-CF-98, K13-CF-99, K13-CF-100

K13-DE-01, K13-DE-02, K13-DE-03, K13-DE-04, K13-DE-05, K13-DE-06, K13-DE-07, K13-DE-08, K13-DE-09, K13-DE-10, K13-DE-11, K13-DE-12, K13-DE-13, K13-DE-14, K13-DE-15, K13-DE-16, K13-DE-17, K13-DE-18, K13-DE-19, K13-DE-20, K13-DE-21, K13-DE-22, K13-DE-23, K13-DE-24, K13-DE-25, K13-DE-26, K13-DE-27, K13-DE-28, K13-DE-29, K13-DE-30, K13-DE-31, K13-DE-32, K13-DE-33, K13-DE-34, K13-DE-35, K13-DE-36, K13-DE-37, K13-DE-38, K13-DE-39, K13-DE-40, K13-DE-41, K13-DE-42, K13-DE-43, K13-DE-44, K13-DE-45, K13-DE-46, K13-DE-47, K13-DE-48, K13-DE-49, K13-DE-50, K13-DE-51, K13-DE-52, K13-DE-53, K13-DE-54, K13-DE-55, K13-DE-56, K13-DE-57, K13-DE-58, K13-DE-59, K13-DE-60, K13-DE-61, K13-DE-62, K13-DE-63, K13-DE-64, K13-DE-65, K13-DE-66, K13-DE-67, K13-DE-68, K13-DE-69, K13-DE-70, K13-DE-71, K13-DE-72, K13-DE-73, K13-DE-74, K13-DE-75, K13-DE-76, K13-DE-77, K13-DE-78, K13-DE-79, K13-DE-80, K13-DE-81, K13-DE-82, K13-DE-83, K13-DE-84, K13-DE-85, K13-DE-86, K13-DE-87, K13-DE-88, K13-DE-89, K13-DE-90, K13-DE-91, K13-DE-92, K13-DE-93, K13-DE-94, K13-DE-95, K13-DE-96, K13-DE-97, K13-DE-98, K13-DE-99, K13-DE-100

K15-14

K15-15

K15-09

01/10/2025 09:04	53.1515	3.9488	STATION 72	SVP	END	64PE54972	72_1	K18-07
01/10/2025 09:04	53.1517	3.9488	STATION 72	Multibeam	BEGIN	64PE549EM30272	72_2	
01/10/2025 11:00	53.0773	3.966	STATION 73	Multibeam	BEGIN	64PE549EM30273	73_1	K18-01
01/10/2025 11:48	53.0738	3.9668	STATION 73	Multibeam	END	64PE549EM30273	73_1	
01/10/2025 12:22	53.0702	4.0542	STATION 74	Multibeam	BEGIN	64PE549EM30274	74_1	L16-15, L16-14
01/10/2025 13:34	53.0688	4.0573	STATION 74	Multibeam	END	64PE549EM30274	74_1	
01/10/2025 14:49	53.2178	4.1793	STATION 75	Multibeam	BEGIN	64PE549EM30275	75_1	L13-15
01/10/2025 15:27	53.2138	4.1802	STATION 75	Multibeam	END	64PE549EM30275	75_1	
02/10/2025 03:56	55.0325	4.524	STATION 76	Funnel Lander	BEGIN	64PE54976	76_1	B17-05
02/10/2025 04:18	55.0307	4.5235	STATION 76	Funnel Lander	END	64PE54976	76_1	
02/10/2025 06:22	55.0295	4.5235	STATION 77	ROV deployment	BEGIN	64PE549ROVDEP77	77_2	
02/10/2025 06:48	55.0297	4.5233	STATION 77	Bubble generator	BEGIN	64PE54977	77_3	
02/10/2025 07:45	55.0313	4.5213	STATION 77	Multibeam	BEGIN	64PE549EM30277	77_4	
02/10/2025 08:48	55.0322	4.5173	STATION 77	Multibeam	END	64PE549EM30277	77_4	
02/10/2025 09:10	55.0302	4.5232	STATION 77	ROV deployment	BEGIN	64PE549ROVDEP77	77_5	
02/10/2025 11:42	55.0298	4.5233	STATION 77	Bubble generator	END	64PE54977	77_3	
02/10/2025 11:47	55.0297	4.5235	STATION 77	ROV deployment	END	64PE549ROVDEP77	77_5	
06/10/2025 12:04	53.3913	4.3602	STATION 78	SVP	END	64PE54978	78_1	L11-01

06/10/2025 12:04	53.3913	4.3602	STATION 78	Multibeam	BEGIN	64PE549EM30278	78_2	
06/10/2025 13:27	53.4227	4.3603	TRANSIT 81	Multibeam	END	64PE549EM30278	78_3	
06/10/2025 13:27	53.4227	4.3603	STATION 79	Multibeam	BEGIN	64PE549EM30279	79_1	L11-07
06/10/2025 14:16	53.4235	4.353	STATION 79	Multibeam	END	64PE549EM30279	79_1	
06/10/2025 14:55	53.4243	4.2455	STATION 80	Multibeam	BEGIN	64PE549EM30280	80_1	L10-08
06/10/2025 15:27	53.4225	4.2418	STATION 80	Multibeam	END	64PE549EM30280	80_1	
06/10/2025 16:38	53.4072	4.2117	STATION 81	Multibeam	BEGIN	64PE549EM30281	81_1	L10-D-01, L10-D-02, L10-D-03, L10-D-04, L10-D-05
06/10/2025 16:38	53.4072	4.2117	STATION 81	Multibeam	END	64PE549EM30281	81_1	
06/10/2025 17:00	53.3948	4.2052	STATION 82	Multibeam	BEGIN	64PE549EM30282	82_1	L10-C-01, L10-C-02, L10-C-03, L10-C-04, L10-C-05, L10-C-06
06/10/2025 17:41	53.3917	4.2	STATION 82	Multibeam	END	64PE549EM30282	82_1	
06/10/2025 19:33	53.5645	4.5727	STATION 83	Multibeam	BEGIN	64PE549EM30283	83_1	L08-09, L08-H-01, L08-H-02
06/10/2025 20:39	53.5638	4.5628	STATION 83	Multibeam	END	64PE549EM30283	83_1	
06/10/2025 22:03	53.6208	4.4795	STATION 84	Multibeam	BEGIN	64PE549EM30284	84_1	L08-03
06/10/2025 22:34	53.6242	4.4735	STATION 84	Multibeam	END	64PE549EM30284	84_1	
06/10/2025 23:09	53.6388	4.5647	STATION 85	Multibeam	BEGIN	64PE549EM30285	85_1	L08-P-01, L08-P-02, L08-P-03, L08-P-05
07/10/2025 00:12	53.6413	4.5648	STATION 85	Multibeam	END	64PE549EM30285	85_1	
07/10/2025 02:06	53.5887	4.9625	STATION 86	SVP	END	64PE54986	86_1	L09-11

07/10/2025 02:06	53.5887	4.9625	STATION 87	Multibeam	BEGIN	64PE549EM30287	87_1	
07/10/2025 02:52	53.585	4.9595	STATION 87	Multibeam	END	64PE549EM30287	87_1	
07/10/2025 03:17	53.6132	4.9392	STATION 88	Multibeam	BEGIN	64PE549EM30288	88_1	L09-12
07/10/2025 04:05	53.6097	4.9408	STATION 88	Multibeam	END	64PE549EM30288	88_1	
07/10/2025 04:12	53.6115	4.9515	STATION 89	Multibeam	BEGIN	64PE549EM30289	89_1	L09-08
07/10/2025 04:36	53.616	4.9502	STATION 89	Multibeam	END	64PE549EM30289	89_1	
07/10/2025 05:02	53.6572	4.9267	STATION 90	Multibeam	BEGIN	64PE549EM30290	90_1	L09-07
07/10/2025 05:54	53.655	4.92	STATION 90	Multibeam	END	64PE549EM30290	90_1	
07/10/2025 07:50	53.6403	4.5627	STATION 91	ROV deployment	BEGIN	64PE549ROVDEP91	91_1	L08-P-01, L08-P-02, L08-P-03, L08-P-05
07/10/2025 09:43	53.64	4.5623	STATION 91	ROV deployment	END	64PE549ROVDEP91	91_1	
07/10/2025 10:00	53.6402	4.5625	STATION 91	CTD with Samples	BOT	64PE549CTDBOT91	91_2	
07/10/2025 11:11	53.64	4.5627	STATION 91	ROV deployment	BEGIN	64PE549ROVDEP91	91_3	
07/10/2025 11:48	53.6398	4.5627	STATION 91	ROV deployment	END	64PE549ROVDEP91	91_3	
07/10/2025 12:48	53.717	4.6588	STATION 92	Multibeam	BEGIN	64PE549EM30292	92_1	L05-07
07/10/2025 13:42	53.7158	4.6512	STATION 92	Multibeam	END	64PE549EM30292	92_1	
07/10/2025 17:09	54.2215	4.5942	STATION 93	Multibeam	BEGIN	64PE549EM30293	93_2	F14-07
07/10/2025 17:48	54.2192	4.5868	STATION 93	Multibeam	END	64PE549EM30293	93_2	
07/10/2025 20:57	53.8623	5.092	STATION 94	Multibeam	BEGIN	64PE549EM30294	94_2	M01-03

07/10/2025 21:53	53.8608	5.0872	STATION 94	Multibeam	END	64PE549EM30294	94_2
07/10/2025 22:01	53.8548	5.0873	STATION 95	Multibeam	BEGIN	64PE549EM30295	95_1
07/10/2025 22:42	53.8542	5.0933	STATION 95	Multibeam	END	64PE549EM30295	95_1
07/10/2025 22:42	53.8542	5.0933	STATION 95	End of Sci progr.	END		

M01-02